

AUTOMATED CONTROL APPROACH FOR INDUSTRIAL W'ELDING TRANSFORMER TO MINIMIZE THE IDLING POWER LOSS

A dissertation submitted to the Department of Electrical Engineering, University of Moratuwa in partial fulfillment of the requirement for the degree of Master of Science

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Abstract

Main objective is to design and implement automated control circuit to switch ON & OFF main power feeding contactor of industrial welding transformer, depend on the work pattern. Voltage sensing at the out put terminals of secondary winding of welding transformer is used as a one and only input signal for the control circuit. Reduced voltage 24 VAC is supplied to primary during idling and during operation it converts in to 400 VAC, and this conversion takes place automatically. By that, able to reduce idling power loss on primary winding due to open circuit core loss & iron loss.

During designing of new system special attention was made, not to change existing conventional welding procedure and not to introduce additional external sensors and cables other than conventional welding electrode and welding cable.

New system was practically implemented in yard and tested for long period of time in different work conditions in Colombo Dockyard PLC. System was tested with existing conventional welders but no behavioral changes were observed during welding operation after implementing new system. Successful trails were carried out and proved it uninterrupt operation.

Under guidance and instructions of my project supervisor I worked and finally able to came up with practically feasible solution. This report describes problem identification, how the design concept developed, power saving and cost benefits .to yard after implementation of new system.

The report starts with an introduction as a 1st chapter where describe the current welding practice at Colombo Dockyard PLC, how to reduce idling power loss by implementing new method and final goal of my project. 2nd chapter describes the statement of the problem and problem identification, new solution and how it affects to save energy.



The 3rd chapter consists with gathered technical data and its analysis during execution of design approach.

Next 4th chapter describe about proposed and implemented solutions for the identified problem and evolution of design concept.

Fifth chapter describes the energy saving calculations and cost benefit analysis. Finally, in the conclusion, I have explained practically and economically viability of new product as a industrial product.

DECLARATION

The work submitted in this dissertation is the result of my own investigation, except where otherwise stated.

It has not already been accepted for any degree, and is also not being concurrently submitted for any other degree.



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Chapter 1

Introduction

1.1 Background about myself and Colombo Dockyard PLC

Colombo Dockyard is the one of the biggest shipyard in Sri Lanka. Main Share Holder is Onomichi Dockyard, Japan. Shipbuilding, Ship Repair, Heavy Engineering and Consultancy & Design Services are the main activities caring out by Colombo dockyard. Today, Colombo Dockyard PLC has earned international recognition as a leading ship repairer and shipbuilder in the South Asia region.

I am an Automation Engineer of Colombo Dockyard PLC and I have been working for last eight years. After obtaining my 1st degree from University of Moratuwa, I joined the Colombo Dockyard PLC as a mechanical engineer on 1st of September 2000. And after 3 years I was appointed as an Automation engineer of the company.

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1.2 Basic Introduction for current work practice at Colombo Dockyard PLC

1.2.1 Current welding procedure which is practicing at yard [4]

Colombo Dockyard PLC is heavily using mainly arc welding transformers during ship hull construction, pipe fabrication work and other steel fabrication works. Total numbers of transforms are 685 Nos. According to the basic electrical theories for transformers, it is obvious by reducing the supply voltage to primary winding it can reduce the idling power loss at primary winding when secondary at open circuit (idling).

Welding transformers which are currently being used in Colombo Dockyard don't have any kind of automated control circuit to switch ON & OFF the supply power depend on the work pattern.

As per the existing system, it consist only manual switch for ON/OFF main power. At the beginning of the day operator comes with his welding cable and connects the cable with the welding transformer and subsequently switch ON the transformer and starts his work.

In general during steel fabrication welder should carry out following preparation work in addition to actual welding operation. It can not omit.

Preparation of fit up Bevel preparation Grinding Gas cutting as per the situation, etc.,

During consecutive continuous welding operations operator has to be carried out above pre preparation operations before next continuous run starts. It can be considerable amount of time and it take 30 minute ,45minute, 1 hour and some times it extends up to 2 or 3 hour depend on the work condition. During that time, transformer may idle. Even though the transformer is idle, as per the existing current practice, 400 VAC [2] gets connects with primary winding and keep on maintain 400 VAC irrespective of the work pattern till the operator switch OFF the transformer by manual switch at the end of the day.

1.2.2 Energy wastage during idle period due to open circuit core loss & iron loss.

As per the existing current practice, during idling time 400 VAC gets connects with primary winding and keep on maintain 400 VAC irrespective of the work pattern. During this idling period secondary winding side is at open circuit. But resultant circulating current (average 10 Amp) f lows through primary winding even transformer at idle condition. Due to this huge circulating current during idling there is a huge energy wastage takes place.

It was measured the active power loss at primary winding during idling, by using active power energy meter.

Specifications of used energy meter, Make: Polyphase Energy meter.

Time @	Reading on energy meter (kWh)
08.30 Hours	2.54
13.53 Hours	6.55
18.48 Hours	10.96

Table 1.1 – Measured power consumption during idling when 400 VAC gets connects with primary

As per above table active power consumption for 10.5 hours = 10.96 - 2.54 = 8.42 kWh

Total power saving calculation will be described on chapter 5.3.

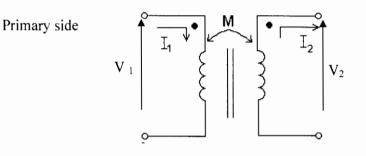
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1.2.3 Specification & general configuration of Welding Transformer at Colombo Dockyard PLC

1.2.3.1 Specification, as per the User Manual of ESAB Transweld 400 [1,2,4]

Make: ESAB India Limited Kolkata Model: Transweld 400 Serial No: 0407305 Supply Voltage: 415 V Frequency : 50 Hz Rated Input Current: 63 Amp Input KVA : 26 KVA Phase: 2 line of 3 Phase Current Range: 80A – 400 A Operating Circuit Voltage: 80 V Max Contentions hard welding current at 60 % duty Cycle – 300 A, Weight: 115 Kg

1.2.3.2 General configuration[3]



Secondary side

Figure 1.1 - General configuration of welding transformer

 V_1 – Supply voltage to primary winding

V2 - Induced Voltage at secondary winding

I₁ - Circulating current at primary winding

I₂ - Circulating current at secondary winding va. Sri Lanka.

- R_1 Total measured resistance of primary winding = 1.0 to 1.3 Ω
- R_2 Total measured resistance of secondary winding = 0.3 to 0.4 Ω

1.2.4 Utilization of arc welding transformers in Colombo Dockyard PLC

Total No of welding transformers in Colombo Dockyard PLC = 685 Nos

Location	No of Transformers
Yard welding pool (Ships on board, new construction work beds, etc,.	574
Metal Workshop (MEW)	40
Pipe Fabrication workshop (PFS)	10
Deck fitting workshop (FIS DEC)	5
Steel workshop	40
Component workshop (COM)	6
Machinery outfitting workshop (MOF)	10
Total	685

Table 1.2 – Utilization of arc welding transformers in Colombo Dockyard PLC

For every 10 hours total time duration, due to idling it will waste 8 kWh for each transformer unit. Total No of T/F is being used in yard is around 685 Nos.

1.3 Goals and Scope of present work

During above mentioned idling period secondary winding is at open circuit. But due to resultant circulating current (average 10 Amp) flow through primary winding, even transformer at idle condition. Due to this huge circulating current there is a huge energy wastage takes place. By reducing the supply voltage from 400 VAC to 24 VAC, can reduce no load current at primary winding from around 10 A to 0.1A.

By injecting reduced voltage (24 VAC) to the primary, able to provide signal to main power feeding contactor to switch "ON" & "OFF" depend upon the work pattern of the operator.

Goal was to invent, design and implement automated control circuit to feed 24 VDC to primary during idling and subsequently if it needs to perform actual welding then automatically 400 VAC gets connect with primary winding. Then welding transformer is ready for welding operation. Subsequently by monitoring idling time duration, if it is more than 3 minutes (most effective time period which was found out from research), it again connects with 24 VAC automatically to save power.

Finally new system was practically implemented in yard and tested for long period of time in different work conditions in Colombo Dockyard PLC. System was tested with existing conventional welders but after implementing new system no behavioral changes were observed during their welding operation. During designing of new system special attention was made not to change existing conventional welding procedure and not to introduce additional external sensors and cables other than conventional welding electrode and cable.

Successful trails were carried out and proved it un-interrupted operation.

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Chapter 2

Statement of the Problem

2.1 Preliminaries

Colombo Dockyard PLC is heavily using mainly arc welding transformers during ship hull construction, pipe fabrication work and other steel fabrication works. Total numbers of transforms are 685 Nos.

As per the existing current practice, during idling time also 400 VAC gets connects with primary winding and keep on maintain 400 VAC irrespective of the work pattern. During this idling period secondary winding side is at open circuit. But resultant circulating current (average 10 Amp) flows through primary winding even transformer at idle condition. Due to this huge circulating current during idling there is a huge energy wastage takes place.

In order to avoid above unnecessary energy wastage during idling only action taken by yard is displaying of sign board on welding transformer by giving instructions to operator to switch off the plant when not in use.

According to the basic electrical theories for transformers, it is obvious by reducing the supply voltage to primary winding it can reduce the idling power loss at primary winding when secondary at open circuit (at idling).

Welding transformers which are currently being used in Colombo Dockyard don't have any kind of automated control circuit to switch ON & OFF the supply power depend on the work pattern. As per the existing system, it consist only manual switch for ON/OFF main power.

At the begging of the day operator comes with his welding cable and connects the cable with the welding transformer and subsequently switch ON the transformer and starts his work and subsequently keep "ON" the plant till the operator finishes his work for the day.

2.2 Problem identification & Thesis statement

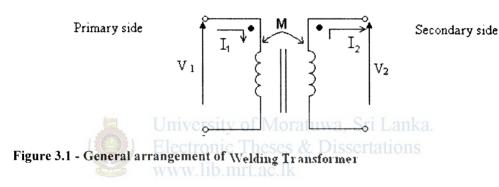
Instruction signboard which was displayed on arc welding transformers which are currently being used in Colombo Dockyard PLC is the initiation point of the project concept. Subjected sign board gives some instructions to operator. It says to **"SWITCH OFF THE WELDING TRANSFORMER WHEN NOT IN USE"**. This sign board directed me to find automated solution to switch OFF the transformer when not in use and simultaneously it gets switch ON automatically when operator need to perform welding operations. By that able to reduce idling power loss on primary winding due to open circuit core loss & iron loss.

Above idea was executed as my final project under my M.Sc/PG Diploma in Industrial Automation 2006/07 course. Named the project as "Automated control circuit for industrial welding transformer to minimize idling power loss"

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Gathered technical data and its Analysis during execution of design approach

3.1 Following are the some of CT out put current and voltage measurements which relevant to each of CT under current sensing design approach



1. $V_1 = 24$ VAC:

> CT Ration: 100 / 5 A @ primary side

Serial	Set loading value	CT Voltage out	CT Current out
No	condition of T/F (ie: Max	put (V)	put (A)
	Current level)		
1	100	0.1 to 0.2	0.02
2	200	0.30	0.06
3	300	0.61	0.11
4	400	0.76	0.17

Table 3.1 - CT out put current and voltage measurements with CT Ration: 100 / 5 A & $V_1 = 24$ VAC

- 2. $V_1 = 400$ VAC:
 - > CT Ration: 100 / 5 A @ primary side

Serial	Set loading value	CT Voltage out	CT Current out
No	condition of T/F (ie: Max	put (V)	put (A)
	Current level)		-
1	No load	0.87	0.20
2	100	0.96	0.96
3	200	0.99	1.54
4	300	1.01	2.21
5	400	1.03	2.92

Table 3.2 - CT out put current and voltage measurements with CT Ration: 100 / 5 A & V1 = 400 VAC

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> CT Ration: 400 / 5 A @ Secondary side

3. $V_1 = 24$ VAC:

Serial	Set loading value	CT Voltage out	CT Current out
No	condition of T/F (ie: Max	put (V)	put (A)
	Current level)		
1	100	3.35	0.04
2	200	3.30	0.10
3	300	2.95	0.17
4	400	2.64	0.24

Table 3.3 - CT out put current and voltage measurements with CT Ration: 400 / 5 A & V₁ = 24 VAC

- 4. $V_1 = 400$ VAC:
 - > CT Ration: 400 / 5 A @ Secondary side

Serial	Set loading value	CT Voltage out	CT Current out
No	condition of T/F (ie: Max	put (V)	put (A)
	Current level)		
1	100	0.21	1.1
2	200	0.39	2.02
3	300	0.57	2.9
4	400	0.77	3.9

Table 3.4 - CT out put current and voltage measurements with CT Ration: 400 / 5 A & $V_1 = 400$ VAC

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3.2 Measured parameters during voltage sensing design

Following are the measured values of I₁ & V₂ by varying transformer current setting (using currant changing regulator) with the constant $V_1 = 400$ VAC This data was gathered relevant to voltage sensing design approach

Set T/F loading condition	I ₁ (A)	V ₂ (V AC)
100	4.0	67.5
200	4.2	70.9
300	4.7	73.0
400	4.9	74.4

Table 3.5 - Measured values of I $_1$ & V $_2$ by varying transformer current setting

3.3 Following are the measured values of primary and secondary parameters when secondary under load.

This data was gathered relevant to voltage sensing design approach

> V_1 = 400 VAC :

Serial No	Set loading value of secondary winding (Max Current at secondary winding)	I 1 (A)	I ₂ (A)	V ₂ (V AC)
1	100	19.7	96.9	26.0
2	200	32.7	154.9	27.9
3	300	42.0	217.0	40.0
4	400	61.5	270.0	42.8

Table 3.6 - Measured values of primary and secondary parameters when secondary under load and $V_1 = 400$ VAC

> V_1 = 24 VAC :

Serial No	Set loading value of secondary winding (Max Current at secondary winding)		& Dissertatio	V_2 (V AC)
1	100	1.2	5.4	0.20
2	200	2.1	10.5	0.39
3	300	3.1	15.7	0.29
4	400	4.3	21.7	0.58

Table 3.7 - Measured values of primary and secondary parameters when secondary under load and $V_1 = 24$ VAC

> V_1 = 48 VAC :

Serial No	Set loading value of secondary winding (Max Current at secondary winding)	I ₁ (A)	I ₂ (A)	V ₂ (V AC)
1	100	2.1	10.27	0.36
2	200	3.6	18.12	0.42
3	300	4.5	21.0	0.78
4	400	5.9	29.7	0.65

Table 3.8 - Measured values of primary and secondary parameters when secondary under load and $V_1 = 48$ VAC

3.4 Behavioral study of welding transformer by connecting various types of step down transformers parallel to primary winding of welding transformer.

In the case of voltage sensing design approach signal to be obtain by connecting small step down transformer with the secondary winding of welding transformer.

Behavior was studied by connecting various types step down transformers parallel to primary winding of welding transformer.

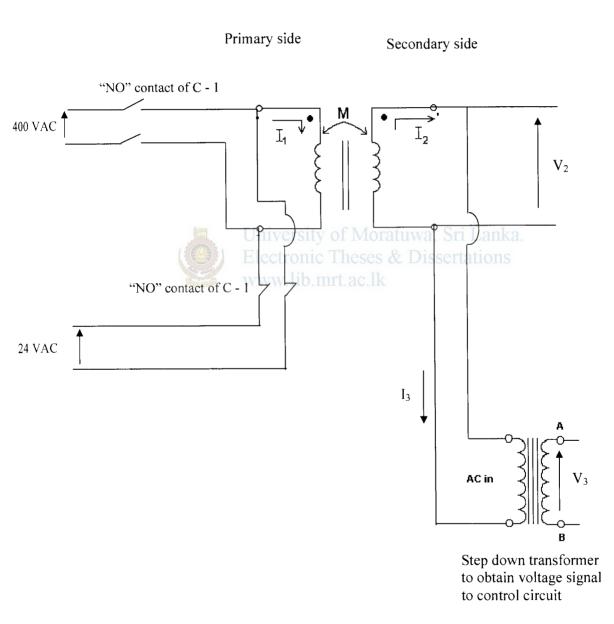


Figure 3.2 - Transformer with external devices during behavioral study

Relevant readings are as follows;

Ser.	Set	During	During welding (On load)				Open circuit (No load)		
No	loading	$I_2(A)$	$I_3(mA)$	$V_2(V)$	$V_3(V)$	$V_2(V)$	$V_3(V)$	I ₃	
	Condition							(mA)	
1	100	6.47	0.79	0.18	0.084	4.59	1.27	7.77	
2	200	10.60	0.84	0.18	0.047	4.83	1.35	7.95	
3	300	15.86	1.20	0.27	0.080	4.81	1.37	8.01	
4	400	22.5	1.58	0.39	0.117	4.86	1.40	8.03	

(a) $V_1 = 24$ V AC with 110 VAC / 24 VAC

Table 3.9 – Readings during behavioral study @ $V_1 = 24$ V AC with 110 VAC / 24 VAC step down transformer.

(a) $V_1 = 48$ V AC with 110 VAC / 24 VAC

Ser.	Set	During	During welding (On load)				Open circuit (No load)		
No	loading	$I_2(A)$	$I_2(A) = I_3 = V_2(V) = V_3(V)$				$V_3(V)$	I ₃	
	Condition		(mA)					(mA)	
1	100	9.7	0.77ive	0.19 of	0.051	9.21 Sr	2.381ka	10.48	
2	200	16.7	1.51	0.45	0.096	9.46	2.50	10.61	
3	300	23.1	1.57	0.39	0.097	9.59	2.50	10.74	
4	400	29.6	2.05	0.63	0.105	9.69	2.52	10.88	

Table 3.10 – Readings during behavioral study @ $V_1 = 48$ V AC with 110 VAC / 24 VAC step down transformer.

(a) $V_1 = 220$ V AC with 110 VAC / 24 VAC

Ser. No	Set	During v	During welding (On load)				Open circuit (No load)		
	loading	$I_2(A)$	$I_3(mA)$	$V_2(V)$	$V_3(V)$	$V_2(V)$	$V_3(V)$	$I_3(mA)$	
1	Condition								
1	100	55.5	2.53	0.88	0.42	43.4	12.0	20.54	
2	200	104.5	3.61	1.55	0.59	44.3	12.27	20.81	
3	300	108	15.6	24	6.63	44.6	12.34	20.81	
4	400	148	15.6	26	6.5 to 8.65	44.7	12.56	20.77	

Table 3.11 – Readings during behavioral study $@V_1 = 220$ V AC with 110 VAC / 24 VAC step down transformer.

Ser. No	Set	During	During welding (On load)				Open circuit (No load)		
	loading	$I_2(A)$	$I_3(mA)$	$V_2(V)$	$V_3(V)$	$V_2(V)$	$V_3(V)$	$I_3(mA)$	
	Condition								
1	100	93	14 to 19	23 to29	5.5 to8.5	68.0	19.15	32.84	
2	200	140	16.65	33 to37	7.6	71.0	17.37	34.22	
3	300	202	16.6	57	11.2	72.8	19.84	35.25	
4	400	286	22.4	59	10.4	74.5	19.13	35.65	

(a) $V_1 = 400$ V AC with 110 VAC / 24 VAC

Table 3.12 – Readings during behavioral study @ $V_1 = 400$ V AC with 110 VAC / 24 VAC step down transformer.

(a) $V_1 = 400$ V AC with 80 VAC / 12 VAC (Resistance of primary winding – 40.9 Ω & resistance of secondary winding – 1.7 Ω

Ser.	Set	During	During welding (On load)				rcuit (No	load)
No	loading	$I_2(A)$	$l_3(mA)$	$V_2(V)$	$V_3(V)$	$V_2(V)$	$V_3(V)$	I ₃
	Condition	150	Unive	rsity of	Moratuw	a, Sri L	anka.	(mA)
Ι	100	93.9	6.2 ect	21 to 27	3.8 to 6.0	68.4	10.44	22.9
2	200	162.1	7.6	33.7	4.8 to 6.0	71.9	10.95	25.8
3	300	186.3	9.7	43.7	5.3 to 7.1	73.2	11.19	27.1
4	400	308.0	10.4	48.3	6.4 to 7.2	75.2	11.48	28.6

Table 3.13 – Readings during behavioral study @ $V_1 = 400$ V AC with 80 VAC / 12 VAC step down transformer.

3.5 Measuring of total idling time and study of operator's behavioral pattern which relevant to each work location.

3.5.1 Why idling can not eliminate during steel fabrication process

In general during steel fabrication welder should carry out following preparation work in addition to actual welding operation.

Preparation of fit up Bevel preparation Grinding Gas cutting as per the situation, etc., During consecutive continuous welding operations operator has to be carried out above pre preparation operations before next continuous run stars. It can be considerable amount of time and it take 30 minute ,45minute, 1 hour and some times it extends up to 2 or 3 hour depend on the work condition. During that time transformer may idled.

3.5.2 Instrument used to measure the idling time and to study operator's work pattern

By using data logger idling time was measured.

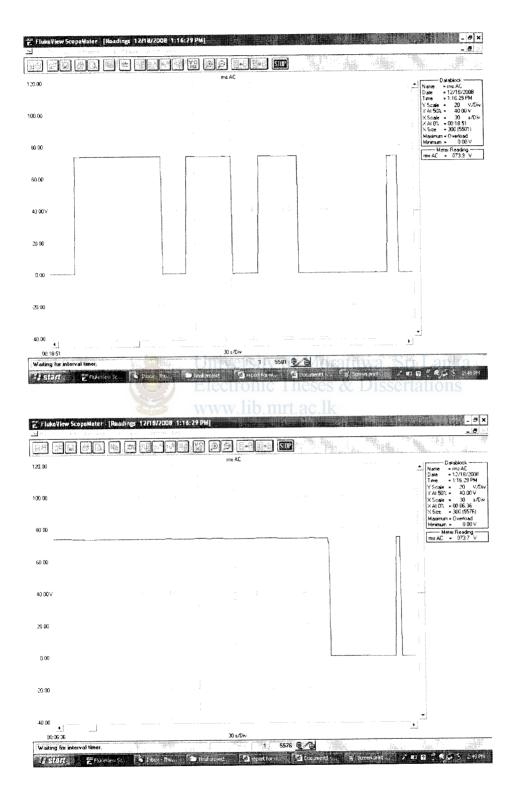
Specification of used data logger: Name of instrument: Fluke View Scope meter [5] Make: Fluke

Model: 105B Series – II

Serial No: DM6720399

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Above instrument was connected with the out put terminals of secondary winding of the welding transformer and it continuously measures the RMS value of terminal voltage. **During idling it is 80 VAC and during operation it drops. By monitoring that voltage level difference, I analyzed the operators welding pattern & total idling time duration.** It was measured which relevant for each work locations and repeated samples were considered. Measurements were taken within 10 hours period for each location.



3.5.3 Sample screen shots during study of operator's work pattern from above SCOPE meter

Figure 3.3 – Sample screen shots during study of operator's work pattern

3.5.4 Data collected which relevant to each work location to measure total idling time for 10 hours of total time period.

Total idling time which relevant to each of following work locates was measured and following are the summarized measured values data. This totalized idling time is measured for total 10 hours period. It was repeated for 5 days.

Location: Yard welding pool (Ships on board, new construction work beds, etc,.

Sample No	Date	Idling Time duration (Hours)
1	2008/10/26	7.50
2	2008/10/27	6.80
3	2008/10/28	5.30
4	2008/10/29	6.50
5	2008/10/30	6.75

Table 3.14 – Measured idling periods at Yard welding pool

Out of 10 hours, average total idling duration: 6.57 Hrs

Location: Metal Workshop (MEW) University of Moratuwa, Sri Lanka.									
Sample No	Date	Idling Time durations & Dissertations							
		(Hours) lib mrt ac lk							
1	2008/10/31	9.40							
2	2008/11/01	7.60							
3	2008/11/02	8.75							
4	2008/11/03	7.25							
5	2008/11/04	6.75							

Table 3.15 – Measured idling periods at Metal Workshop (MEW)

Average: 7.95 Hrs

Location: Pipe Fabrication workshop (PFS)

Sample No	Date	Idling Time duration (Hours)
1	2008/11/05	5.20
2	2008/11/06	4.60
3	2008/11/07	6.00
4	2008/11/08	6.25
5	2008/11/09	6.50

Table 3.16 – Measured idling periods at Pipe Fabrication workshop (PFS)

Average: 5.71 Hrs

Location: Deck fitting workshop (FIS DEC)

Sample No	Date	Idling Time duration
		(Hours)
1	2008/11/10	4.25
2	2008/11/11	5.50
3	2008/11/12	4.75
4	2008/11/13	3.50
5	2008/11/14	6.25

Table 3.17 – Measured idling periods at Deck fitting workshop (FIS DEC)

Average : 4.85 Hrs

Location: Steel workshop

Sample No	Date	Idling Time duration	
		(Hours)	
1	2008/11/15	7.25	
2	2008/11/16	7.60	
3	2008/11/17	7.00 iversity of Mo	ratuwa, Sri Lanka.
4	2008/11/18	6.50 ctronic Theses	& Dissertations
5	2008/11/19	6.00	7

Table 3.18 - Measured idling periods at Steel workshop

Average : 6.87 Hrs

Location: Component workshop (COM)

Sample No	Date	Idling Time duration (Hours)
1	2008/11/20	3.25
2	2008/11/21	5.50
3	2008/11/22	4.75
4	2008/11/23	6.25
5	2008/11/24	7.00

Table 3.19 – Measured idling periods at Component workshop (COM)

Average : 5.35 Hrs

Location: Machinery	outfitting	workshop	(MOF)
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Sample No	Date	Idling Time duration
×		(Hours)
1	2008/11/25	6.50
2	2008/11/26	4.75
3	2008/11/27	5.50
4	2008/11/28	5.25
5	2008/11/29	7.25

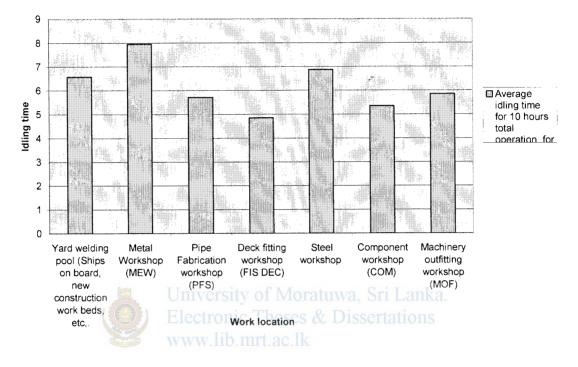
Table 3.20 – Measured idling periods at Machinery outfitting workshop (MOF)

Average : 5.85 Hrs

Summary:

Location	No of Transformers	Average idling time for 10 hours total operation for individual T/F unit (Hours)
Yard welding pool (Ships on board, new construction work beds,	574	6.57
etc,. Univer	sity of Morat	uwa. Sri Lanka
Metal Workshop (MEW)	T40 8	7.95
Pipe Fabrication workshop (PFS)	10 10	5.71
Deck fitting workshop (FIS DEC)	10.mrt.sc.ik	4.85
Steel workshop	40	6.87
Component workshop (COM)	6	5.35
Machinery outfitting workshop	10	5.85
(MOF)		
Total	685	43.15

Table 3.21 – Summary of measured average idling periods which relevant to each work location



Average idling time for 10 hours total operation for individual T/F unit (Hours) VS Work Location

Figure 3.4 – Graphical representation of measured average idling periods which relevant to each work location

Average idling for individual T/F unit at each work location for total 10 hours duration = 43.15 / 7 = 6.16 Hours

3.5.5 Study of operator's work pattern during general welding operation in order to decide the best timer setting which relevant to voltage sensing approach.

This pattern was studied with in one continuous welding run.

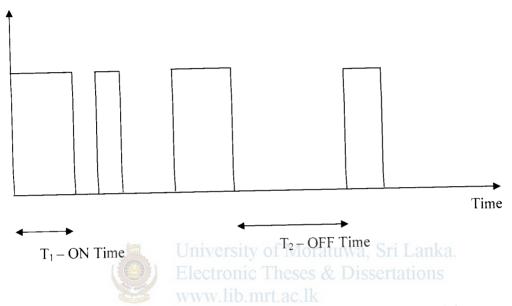


Figure 3.5 – Study of operator's work pattern during each continuous welding run

T₁ - Time for actual continuous welding operation

 T_2 - Time for idling within the consecutive continuous welding operation with in one continuous run.

Studied the work pattern and measured the above $T_1 \& T_2$ values which relevant to each work locations. Found that during continuous welding operation, the operator takes small brake to change the welding electrodes, etc. In order to determine that time period, used the same data logger as mentioned above.

Following are the summarized measured values.

Location: Yard welding pool (Ships on board, new construction work beds, etc,. Date : 2008/10/26

Idling sample No	T ₂ idling time with in one continuous welding run (Sec)
1	165
2	150
3	160
4	180
5	175

Table 3.22 – Measured idling period during each continuous welding run, Location: Yard welding pool

Average idling duration: 166 Sec = 2.7 minutes

Location: Metal Workshop (MEW) Date: 2008/10/31

Idling sample No	T ₂ idling time with in one continuous welding run (Sec)	
1	50	University
2	80	Etaotronio
3	110	Electionic
4	85	www.lib.n
5	70	

Table 3.23 – Measured idling period during each continuous welding run, Location: Metal Workshop (MEW)

Average idling duration: 79 Sec = 1.3 minutes

Location: Pipe Fabrication workshop (PFS) Date: 2008/11/05

Idling sample No	T ₂ idling time with in one continuous welding run (Sec)
1	120
2	150
3	165
4	110
5	95

Table 3.24 – Measured idling period during each continuous welding run, Location: Pipe Fabrication workshop (PFS)

Average idling duration: 128 Sec = 2.1 minutes

Location: Deck fitting workshop (FIS DEC) Date: 2008/11/10

ldling sample No	T ₂ idling time with in one continuous welding run (Sec)
1	70
2	55
3	130
4	140
5	165

Table 3.25 – Measured idling period during each continuous welding run, Location: Deck fitting workshop (FIS DEC)

Average idling duration: 112 Sec = 1.8 minutes

Location: Steel workshop Date: 2008/11/15

Idling sample No	T ₂ idling time with in one continuous welding run (Sec)	
1	100 University of Morat	uwa, Sri Lanka
2	135 (Electropic Theses 8	
3	80	
4	175 www.lib.mt.ac.lk	
5	160	

Table 3.26 – Measured idling period during each continuous welding run, Location: Steel workshop

Average idling duration: 130 Sec = 2.1 minutes

Location: Component workshop (COM) Date: 2008/11/20

ldling sample No	T ₂ idling time with in one continuous welding run (Sec)
1	65
2	50
3	80
4	140
5	120

Table 3.27 – Measured idling period during each continuous welding run, Location: Component workshop (COM)

Average idling duration: 91 Sec = 1.5 minutes

Location: Machinery outfitting workshop (MOF) Date: 2008/11/25

Idling	T_2 idling time with in
sample No	one continuous welding
	run (Sec)
1	85
2	95
3	105
4	170
5	165

 Table 3.28 – Measured idling period during each continuous welding run, Location: Machinery outfitting workshop (MOF)

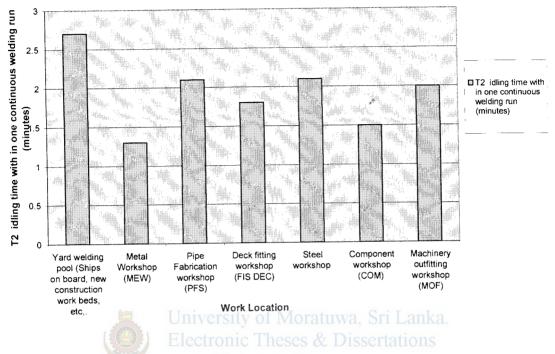
Average idling duration: 124 Sec = 2.0 minutes



Location	T ₂ idling time with in one continuous welding run (minutes)	
Yard welding pool (Ships on board, new construction work beds, etc,.	2.7	
Metal Workshop (MEW)	1.3	
Pipe Fabrication workshop (PFS)	2.1	
Deck fitting workshop (FIS DEC)	1.8	
Steel workshop	2.1	
Component workshop (COM)	1.5	
Machinery outfitting workshop (MOF)	2.0	

Table 3.29 – Summary of measured average idling period during each continuous welding run, For each work location

Average: 115.7 Sec = 1.92 minutes



T2 idling time with in one continuous welding run (minutes) VS Work location

Figure 3.6 – Graphical representation of summarized measured average idling periods during each continuous welding run for each work location

Idling time with in one continuous welding run is nearly below 3 minuets.

By considering above and other all practical aspects decided to keep general timer setting as 3 minuets. But operator can change it further depend on the operator's work pattern. Adjusting facility for timer setting was provided by the proposed control circuit. If operator needs to change he can change it accordingly.

Proposed and implemented solutions

4.1 Design approach and evolution of design concept

Circulating open circuit current was measured at primary depends on the input supply voltage

Following are the measured data by varying V_1 when secondary in open circuit (no load)

V ₁ (V AC)	$\mathbf{I}_{1}(\mathbf{A})$	$\bigcup V_2(VAC)$	Mdra(A)wa, Sri Lani	
24	0.1 to 0.2	Elec.49nic T	nese9 & Dissertation	
48	0.3	ww 9.31b.mrt	ac.10	
110	1.6	10.7	0	
220	7.4	44.0	0	
400	10.3	74.4	0	

Table 4.1 - Measured data by varying V_1 when secondary in open circuit (no load)

It is obvious when reducing the supply voltage to primary winding (V_1) it is drastically reduced that the no load circulating current (I_1) at primary winding. Due to heavy no load circulating current at primary winding there is a huge power loss when transformer at idling. By supplying reduced voltage to primary winding can reduce the idling power loss.

4.2 Design concept – 1

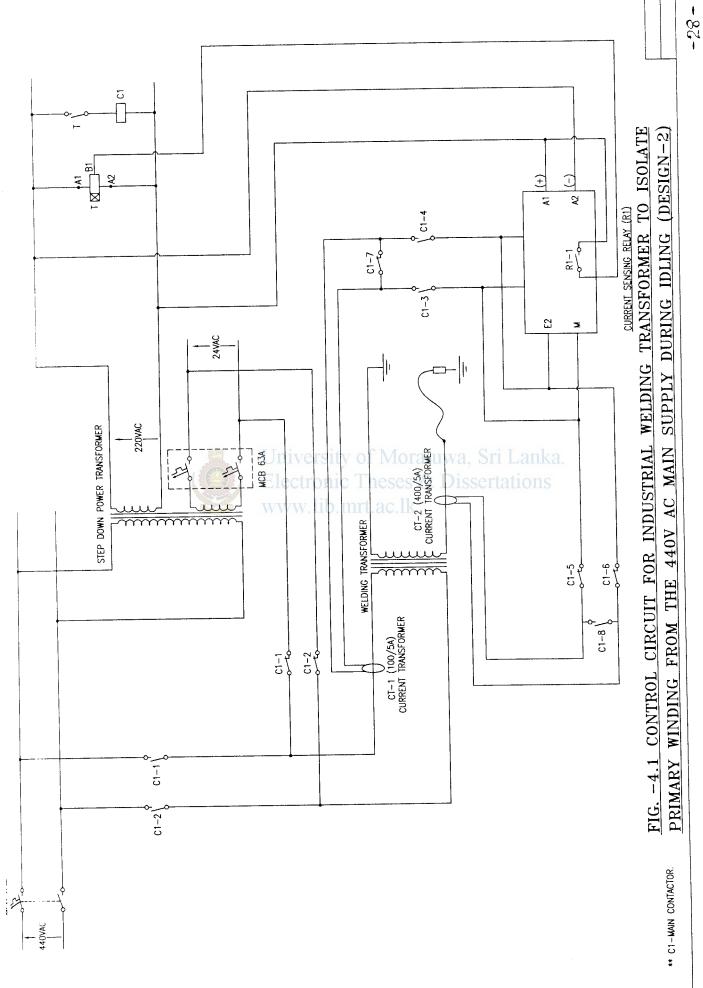
At the beginning of project tried to develop control strategy by keeping primary winding of welding transformer at open circuit. Tried to find sensing method, by implementing vibration sensor or by injecting high frequency signal to the system. But unable to came up with feasible and economical solution.

4.3 Design concept – 2 (Current sensing approach)

Next decided to feed reduce voltage to primary winding and subsequently tried to developed control strategy by sensing circulating current at primary and secondary windings. Two current transformers (CT) were introduced to the system. One is for primary winding (having rating 100A / 5 A) and other is for secondary winding (having rating 400 A / 5 A). Primary side CT is to sense initial starting and secondary side CT is to sense actual welding operation during continuous welding run. Both CT signals were subsequently fed to one current sensing relay module, one at a time and tried to obtain out put from it.

4.3.1 Why current sensing approach was not feasible.

During idling primary side CT (100A / 5 A) connects with current sensing relay through auxiliary "NC" contacts of main power supply feeding contactor. During operation secondary side CT (400 A / 5A) connects with current sensing relay through auxiliary "NO" contacts of main power supply feeding contactor. Expected instant signal from subjected current sensing relay, just after touches the welding electrode with ground. But practically it was failed due to hysteresis characteristics of the current sensing relay. Its minimum hysteresis value is 0.5 % and beyond that unable to reduce. Also the cost of current sensing relay is high. Due to those reasons current sensing approach was not feasible.



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4.4 Design concept – 3 (Voltage sensing approach No – 1)

Hear also reduce voltage is fed to primary winding and subsequently tried to developed control strategy by sensing terminal voltage at secondary winding. One step up power transformer with primary 5 VAC & secondary 24 VAC and one step down power transformer with primary 80 VAC & secondary 24 VAC were introduced to the system in order to provide sensing signals.

4.4.1 Operating procedure

Step -1; initially main power feeding contactor is at de-energized state.

Step – 2; 24 VAC supply connect with primary winding of the welding transformer through auxiliary contacts (NC) of main power feeding contactor. Then subsequently 5 VAC output voltages generates at the out put terminals of secondary winding of welding transformer. This 5 VAC converted in to 24 VAC by the step up power transformer and subsequently resultant 24 VAC connects with control relay (having 24 VAC relay coil) through auxiliary contacts (NC) of main power feeding contactor. In order to increase the sensitivity used 5 VAC / 24 VAC step up transformer. So subjected control relay gets energized during idling and subsequently resultant signal feeds to the timer through "NC" contact of control relay.

Step -3; If welder wants to start his welding operation normally he touches the welding electrode with the ground and subsequently terminal voltage of secondary winding of welding transformer drops and then above control relay gets deenergized and resultant signal sends to timer and subsequently timer gives signal to energize main power feeding contactor.

Step - 4; Then 400 VAC connects with primary winding of welding transformer.

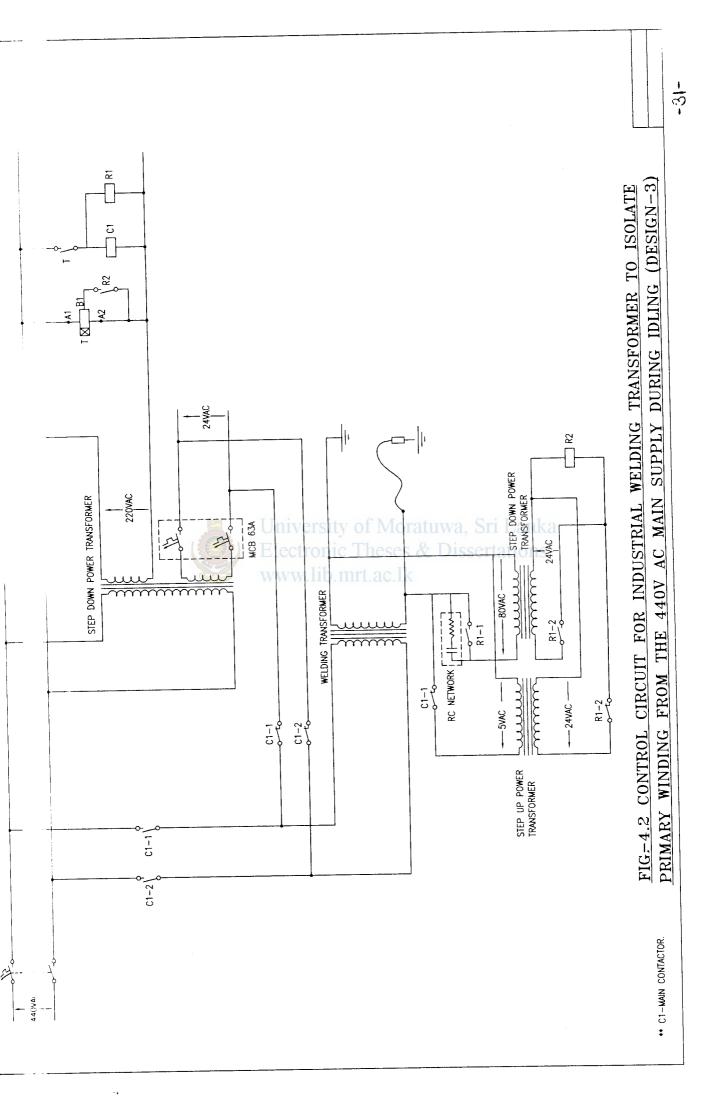
Step – 5; Now welding transformer is ready for actual welding operation.

Step – 6; At this stage open circuit voltage at terminals of secondary winding of welding transformer is 80 VAC. This 80 VAC gets connect with step down power transformer with primary 80 VAC & secondary 24 VAC through the auxiliary contacts (NO) of main power feeding contactor. This resultant 24 VAC connects with same above control relay coil and subsequently it gets energized. Due to each actual welding operation above control relay gets de-energized and resultant signal feeds to timer and subsequently timer gets reset and shifts its time counting. That means along with each welding operation timer gets reset and shifts forward.

Step – 7; If above reset signal is failed to provide with in the set time period then timer gives signal to main power feeding contactor to de-energized and subsequently again 24 VAC supply connect with primary winding of the welding transformer through auxiliary contacts (NC) of main power feeding contactor.

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Step - 8; Now the system converts back to initial condition.



4.5 Design concept – 4 {Final}, Voltage sensing approach No – 2

4.5.1 Difference between Design concept -3 & Design concept -4

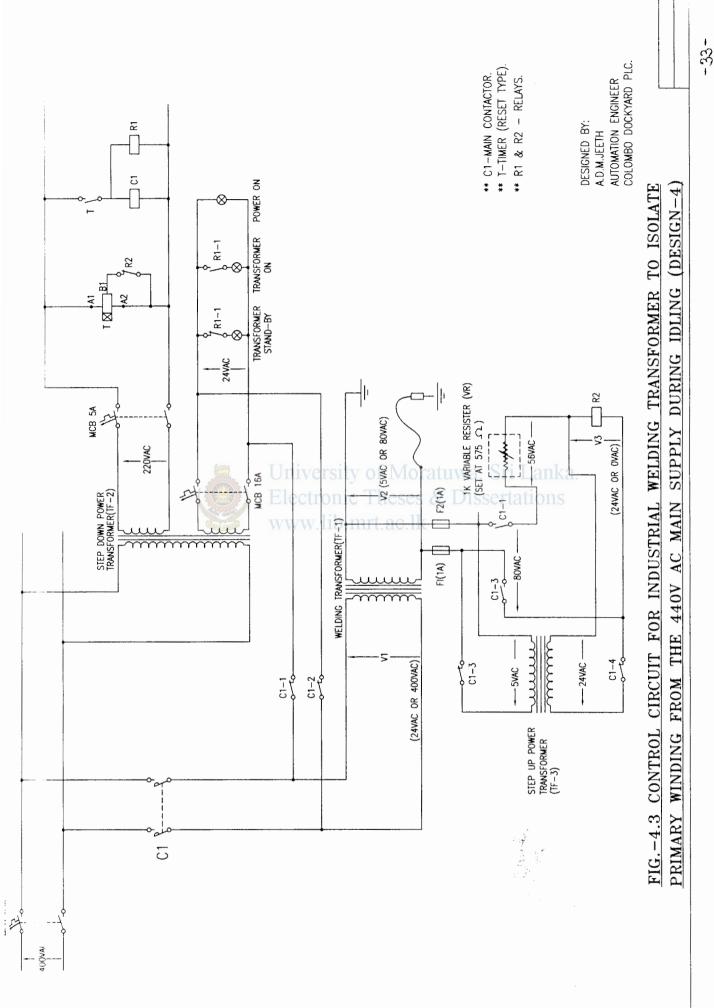
Following is the only difference between Design concept -3 & Design concept -4

Hear avoided one above step down power transformer which having primary 80 VAC & secondary 24 VAC. Instead of above step down power transformer, hear introduced variable resister which is set at 575 Ω in order to cover all operating ranges.

During operation 400 VAC connects with primary winding of welding transformer and resultant 80 VAC generates by the secondary winding.

Above 80 VAC gets connect with above same control relay coil together with series variable resistance through the auxiliary contacts (NO) of main power feeding contactor. Resultant is again 24 VAC supply to control relay coil and rest 56 VCA drops through above variable resistance. Due to each actual welding oration above control relay gets de-energized and resultant signal feeds to timer and subsequently timer gets rest and shifts its time counting. That means along with each welding operation timer gets reset and shifts forward. Same procedure as Design concept -3

Rest of all other steps of operation sequences are same as Design concept - 3



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4.5.2 Calculation of resister value for Variable resister which has used in control circuit.

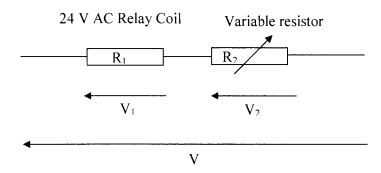


Figure 4.4 – Resistor arrangement to maintain required voltage across relay (R₁)

Specification of subjected relay (R_1) ;

Make: OMRONUniversity of Moratuwa, Sri Lanka.Type : MY- 4Electronic Theses & DissertationsRated supply coil voltage : 24 VAC.lib.mrt.ac.lkResistor value of relay coil : 156 Ω

- $R_1~$ Resistor value of 24 V AC relay coil = 156 Ω
- R_2 Resistor value of Variable resistor
- V₁ Voltage drop across R1
- V₂ Voltage drop across R2
- V Total voltage drop across R1 & R2

Open circuit voltage (during idling) across secondary winding terminals of welding transformer is vary from 68 V AC to 75 V AC depend on transformer current setting.

Short circuit voltage (during welding operation) across secondary winding terminals of welding transformer is vary from 23 V AC to 57 V AC depend on transformer current setting.

Minimum voltage (V) that can apply across both R1 & R_2 to energize relay during open circuit (when transformer in idling) = 68 V AC

Maximum voltage (V) that can apply across both R1 & R_2 to de-energize relay during short circuit (when transformer in operational) = 57 V AC

By measuring following characteristics were found for relay coil; Minimum voltage to energized subjected relay = 16 V ACMax voltage to de-energize relay = 10 V AC

Using ohms low [6] and doing repeated calculations for different values for R_1 found best value for $R_1 = 575 \Omega$, in order to cover all above voltage ranges depends on all current settings.

4.6 Operation procedure according to the final design.

Operation Procedure;

(A) Initial condition:

- 1. C1 at de-energize condition
- 2. 24 VAC connects with the primary winding of welding transformer (TF-1) through the "NC" of C1
- Out put voltage of secondary winding of welding transformer is around 5 VAC
- 4. Above 5 VAC connects with primary winding of step up transformer (TF-3) and it generates 24 VAC out put at the secondary winding of TF-1 and it connects with R2 (24 VAC relay) and R2 gets energized.
- 5. Reset signal for timer (T) gets open through "NC" contact of R2

(B) How it converts to running condition;

- 1. Once welding electrode touches with ground
- 2. R2 gets de-energize.
- 3. Reset signal for timer gives through "NC" contact of R2 and timer starts counting.
- 4. Timer gets energized and it gives signal to energize C1
- 5. 400 VAC connects with primary winding of welding transformer (TF-1) through the "NO" of C1
- 6. Now T/F is ready for welding operation
- 7. After connects 400 VAC with primary, out put voltage of secondary winding of welding transformer increases up to 80 VAC
- Above 80 VAC connects with series combination of R2 & variable resister (set at 575 Ω) and resultant 24 VAC out put connects with R2. Then R2 gets energize.
- 9. Again reset signal for timer (T) gets open through "NC" contact of R2
- 10. If welding operation performs (welding electrode touches with ground) above80 VAC gets drops and R2 gets de-energize.
- 11. Reset signal generates for timer (T) and timer gets reset and starts counting.
- 12. Due to every welding operation timer gets rest and keeps on counting and shifts forward.
- 13. If it fails to generate next reset signal for timer within the set time (3 minutes) that means no welding performs, then T gets de-energized. C1 also de-energized. Again 24 VAC connects with the primary winding of welding transformer. Transformer at idle condition and converts it to initial condition.

4.7 Functional block diagram according to the final design.

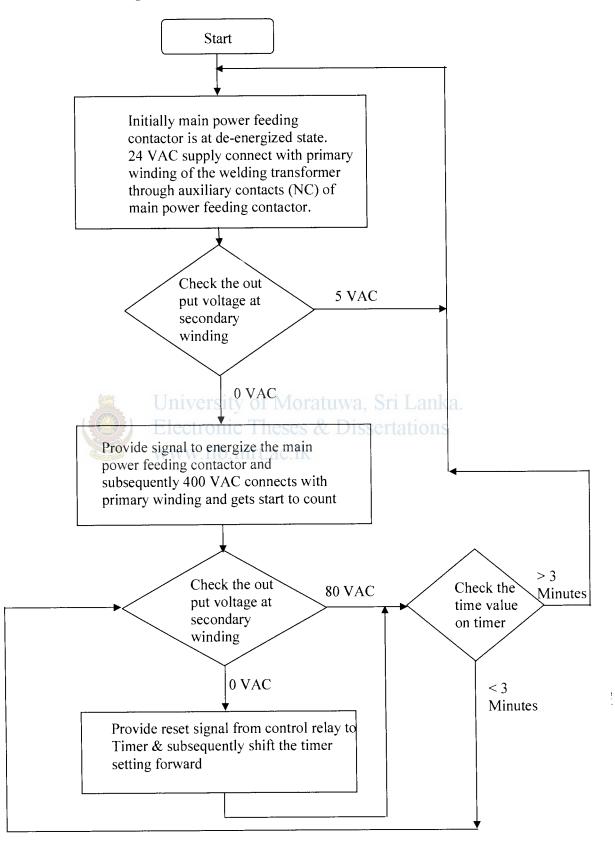


Figure 4.5 - Functional block diagram according to the final design.

Energy saving calculations and cost benefit analysis.

5.1 Material used for control circuit and their cost

Item	Description	Qty	Unit price	Total price
	Description			-
No			Rs.	Rs.
1	Timer with reset facility, supply : 220			
	VAC University of	1 No	3,000.00	3,000.00
2	Magnetic contactor, supply 230 VAC	eses &	Dissertat	ions
	coil ,2 Pole www.lib.mrt.	1 No	6,000.00	5,000.00
3	Control relay MY-2, 24 VAC	1 No	250.00	250.00
4	Control Relay, 220 VAC Coil voltage,			
	2 Pole	1 No	350.00	350.00
5	Step down power transformer, Primary			
	400 VAC & Second 24 VAC, 230			
	VAC			
		1 No	700.00	700.00
6	Step up power transformer, Primary 5		500.00	500.00
	VAC & Second 24 VAC	l No		
7	Variable resister, 1K	1 No	40.00	40.00
8	Powder coated weather proof metal		1,325.00	1,325.00
	enclosure			
	Size: 400 x 300 x 150 mm	l No		
	Total			Rs.11,165.00

Table 5.1 – Material list for one unit with their prices

1

5.2 Measuring of actual active power consumption of welding T/F when idling with out implementing new system

It was measured by using active power energy meter. Specifications of used energy meter as follows.

Specifications of the used energy meter: Make : Polyphase Energy meter

Reading on energy
meter (kWh)
2.54
6.55
10.96

Table 5.2 - Measured data about active power consumption of welding T/F when idling with out implementing new system

As per above table active power consumption for 10.5 hours = 10.96 - 2.54 = 8.42 kWh

5.3 Energy saving calculation [7]

During general steel fabrication operation, If transformer uses for average 10 hours per day generally it will idle around 6 hours (60 %). as per the measurement taken as mentioned under chapter 4.6.4

Power loss during above idling 6 hours $[8] = (8.42 \text{ kWh} / 10.5 \text{ hours}) \times 6 \text{ hours} = 4.81 \text{ kWh}$

For one T/F power loss per day = 4.5 kWh

Total No of T/F in yard in operational = 685 Nos Total power loss per day for all transformer units = $685 \times 4.5 = 3082.5$ kWh

Total loss = 3082 Units CEB average charge per unit = Rs. 7.00 Total loss per day = 3082 x 7 = Rs. 21,574.00 Say No of working days per month: 25 days Total No of working days per year = 300 days Average annual loss for all 685 Nos of transformers = 300 x 21,574.00 = Rs. 6,472,200.00

5.4 Calculation of simple pay back period [7]

Average annual loss = $300 \times 21,574.00 = \text{Rs.} 6,472,200.00$ Total material cost to make one control unit for one unit = Rs. 11,165.00 Total No of T/F in yard in operational = 685 Nos Total material cost for all 685 Nos of units = Rs. 7,648,025.00 Simple pay back period = = Rs. 7,648,025.00 / Rs. 6,472,200.00 = 1.2 years

5.5 Comparison between active power consumption of welding T/F when idling with & with out implementing new system for one machine.

Time	Reading on energy meter	Reading on energy meter
	(kWh) with out	(kWh) with implementing
	implementing new system	new system
08.30 Hours	2.54	10.960
13.53 Hours	6.55	11.183
18.48 Hours	10.96	11.407

Table 5.3 - Reading observed from energy meter

Time	Reading on energy meter	Reading on energy meter
	(kWh) with out	(kWh) with implementing
	implementing new system	new system
08.30 Hours	0.00	0.000
13.53 Hours	4.01	0.223
18.48 Hours	8.42	0.447

Table 5.4 – Actual energy consumption after deducting initial meter reading.

Summary

Before implementing new system active power consumption for 10.5 hours = 10.96 - 2.54 = 8.42 kWh

After implementing new system active power consumption for 10.5 hours = 11.407 – 10.960 = 0.447 kWhUniversity of Moratuwa, Sri Lanka. Electronic Theses & Dissertations

Power saving for 10.5 hours, between new and old conventional system = 8.420 - 0.447 = 7.973 kWh

Chapter 6

Conclusion

New system was practically implemented and tested for long period of time in different work conditions in Colombo Dockyard PLC with existing conventional welders but no behavioral changes were observed after implementing new system. Key point is during designing made special attention not to change existing conventional welding procedure and not to introduce additional external sensors and cables other than conventional welding electrode and cable. After implementing proposed system for all welding transformers in yard it will be a great economical benefit to yard and by saving energy it will be a solution and benefit to existing power crisis of Sri Lanka. Even it can manufacture and sell as a commercial product.

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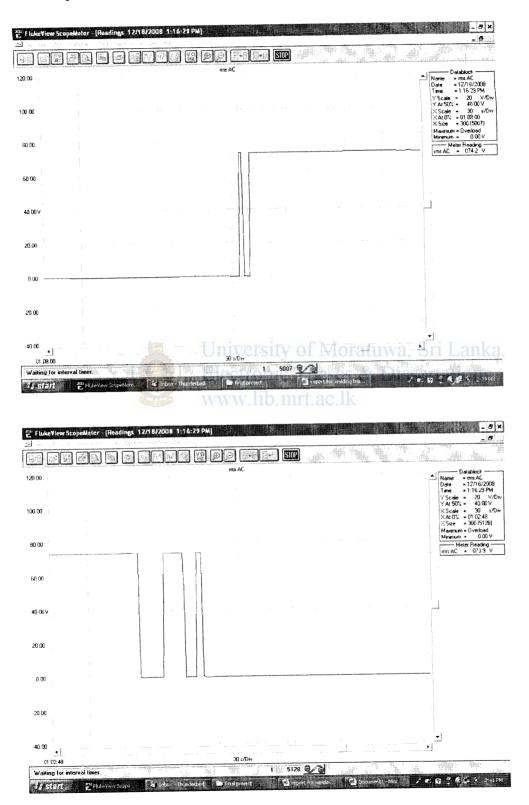
Voltage sensing boards [9], which are currently available in market, can be used in order to sense voltage levels at the output terminals of secondary winding. Subsequently can produce signals for control system. But only problem is those voltage sensing board are very expensive. And difficult to use those in rugged environment, like ship building industry. So suggested design is very cheep and it can use and already proved its operation in rugged environment.

References:

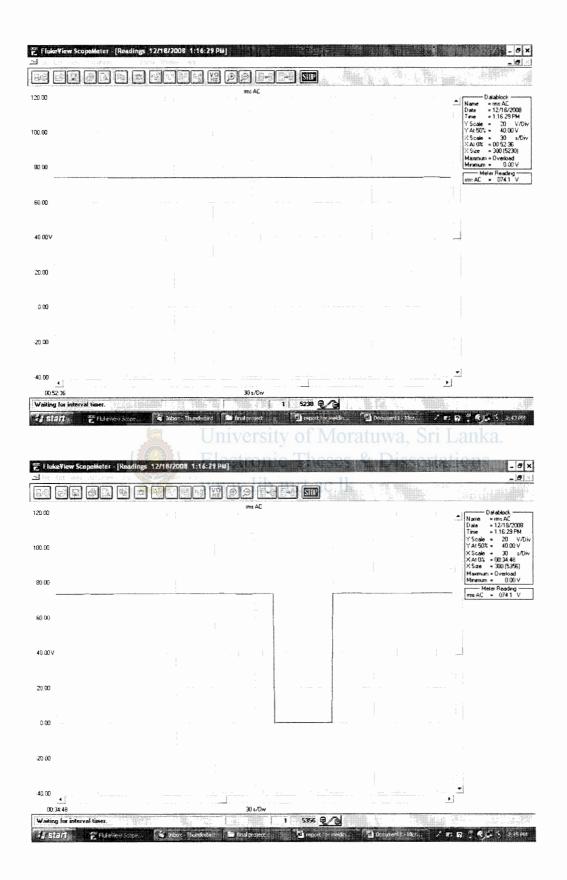
- [1] http://www.esabindia.com/, Official WEB of ESAB India.
- [2] <u>http://www.indiamart.com/ardentengineers/pcat-docs/standard-arc-equipment_10679914.pdf</u>, OEM Specifications of air cooled arc welding transformer Make: ESAB India Limited Kolkata, Model: Transweld 400.
- [3] http://www.sail.co.in/IPSS/1-07-001-95.pdf, INTER PLANT STANDARD STEEL INDUSTRY, SPECIFICATIONS FOR ARC WELDING TRANSFORMERS (THIRD REVISION).
- [4] User Manual of subjected arc welding transformer,Make: ESAB India Limited Kolkata, Model: Transweld 400.
- [5] User Manual of Fluke Scope Meter 105 B Series II, 0/1-Mar-1996.
- [6] <u>http://www.physics.ncsu.edu/courses/pylabs/212/docs/212_OhmsLaw.pdf</u>, Ohms Low and Combinations of Resistors, PY 212.
- [7] Moncef Krarti, "ENERGY AUDIT OF BUILDING SYSTEMS, An Engineering Approach, October 2000.
- [8] http://en.wikipedia.org/wiki/AC_power, Calculation of AC Power.
- [9] http://www.rossengineeringcorp.com/voltage_level_sensor.htm , ROSS ENGINEERING CORPORATION, VOTAGE LEVEL SENSOR/INTERLOCK CIRCUITS AND MODULES.

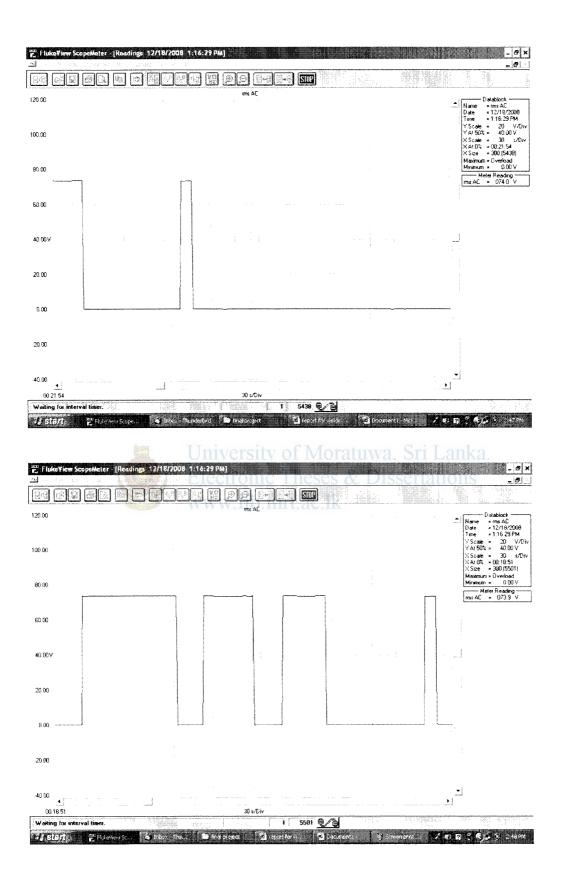
APPENDIX – A: Sample screen shots during study of operator's work pattern from FLUKE SCOPE meter

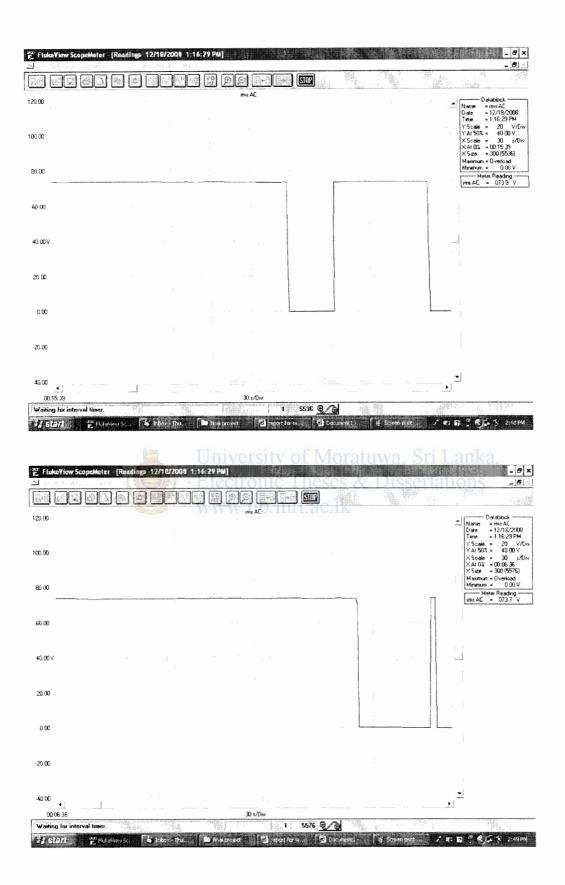
A.1 Sample screen shots

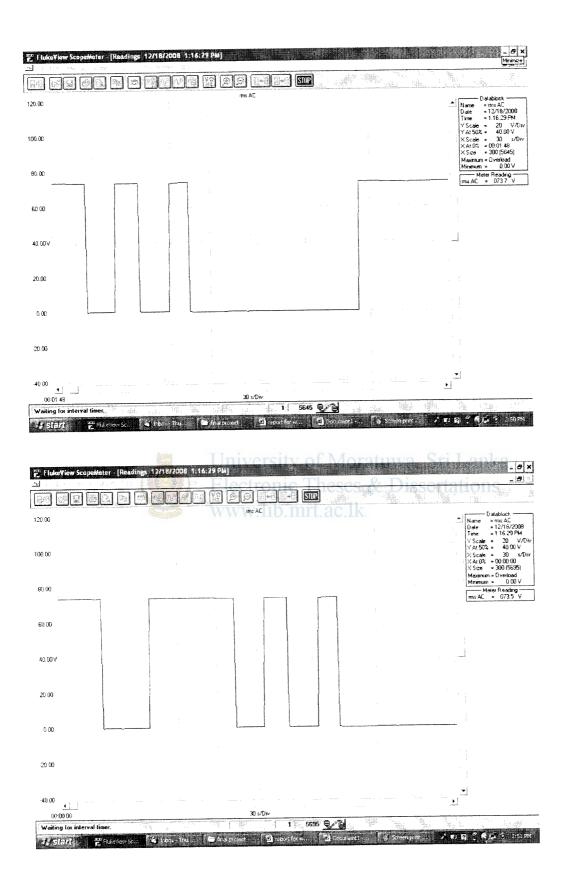


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APPENDIX – B: Literature about instrument and equipments which were used

B.1 Attached following are some literature about instrument and equipments which were used during my project.

- 1. Timer
- 2. Current sensing relay
- 3. Current Transformers (CT)
- 4. Information about SCOPE Meter which was used for data logging.
- 5. Information about voltage sensing available in market [9]



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88 Products

	Reclamation	Arc Equipment	Industrial Gas	Environment	Cuttting Syste	ems
0 (13 5	Consumables	•	- Equipment	➡ Products	•	•

Transweld 400 - Air cooled welding transformer

ESAB Transweld 400 is a 400 Amp Manual Arc Welding Transformer that combines unique functional and safety features. Ensures excellent welding quality with economy. Its natural air-cooled ensures non-stop performance even in the most uncertain difficult conditions. Ideal for use at site or in a workshop.



Special Features

University of Moratuwa, Sri Lanka

- Natural air cooled machine ensures maximum safety
- Current available in single range. Current indicator and current control handle both on front panel
- Robust and compact construction ability to withstand rough handling at sites
- Horizontal shunt core travel ensures precise setting after prolonged use
- Class 'H' insulation provides longer coil life

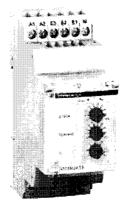
Ordering No.

461-0641-400

Technical Specifications

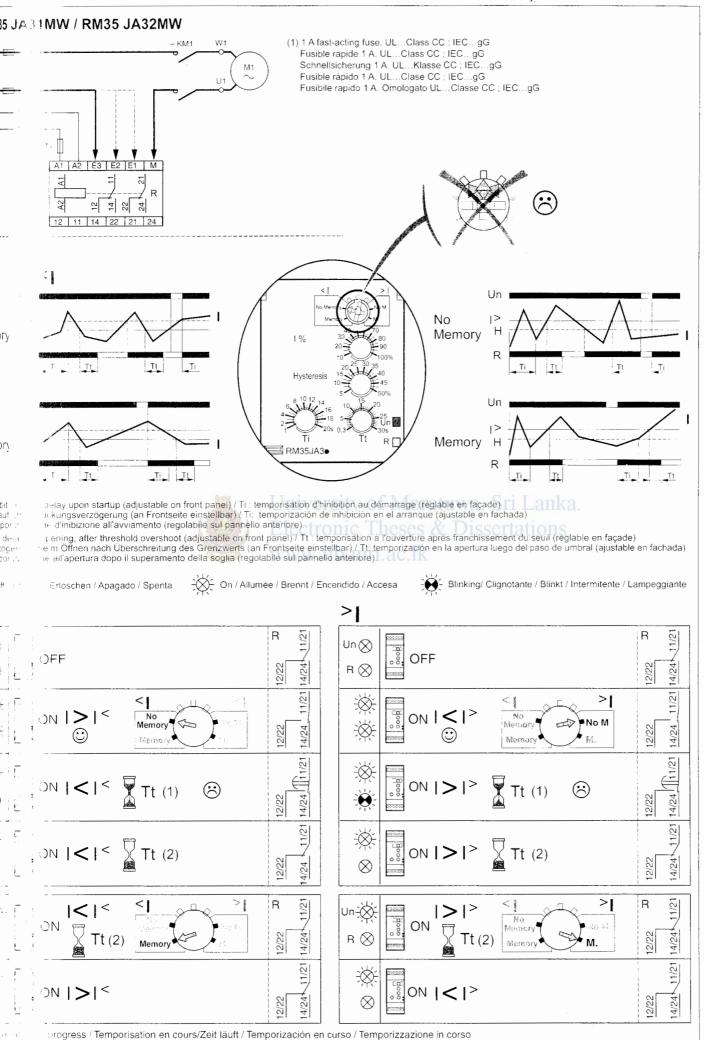
Input	
Supply Voltage	415V, 2 Lines of 3 Phases, 50Hz AC
Rated Input Current	63 Amps
Rated Input KVA	26 KVA
Output	
Open Circuit Voltage (Maximum)	80 V
Range of Welding Current	80 - 400 Amps
Maximum Continuous Hand Welding current at 60% duty cycle (Rated welding current)	300 Amps
Type of welding current regulation	Stepless
Type of cooling	Natural Air Cooled
Net Weight (Approx).	115 Kgs
Approx. Dimension	600 x 410 x 720 mm

Specification about current control relay that has used



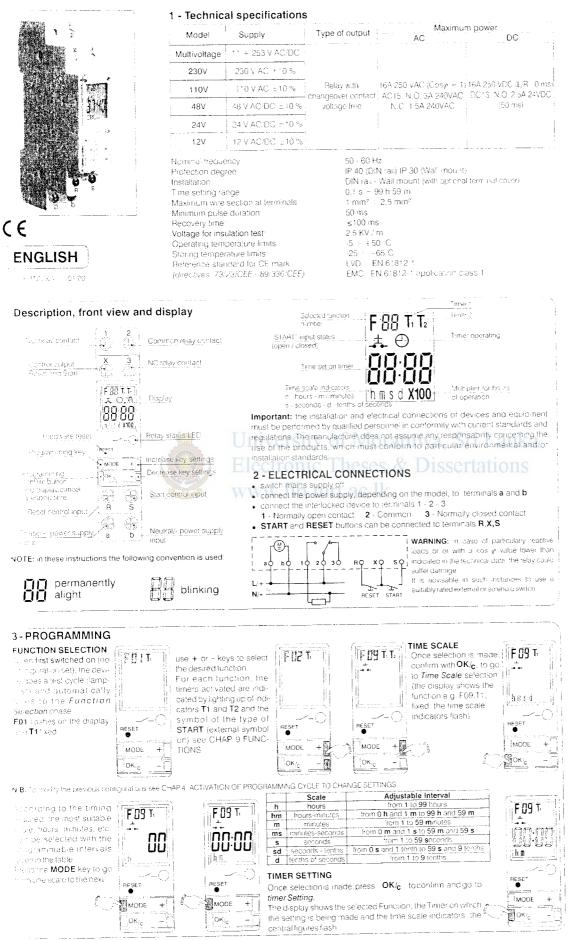


Current control relay RM35JA32MW [RM35JA32MW] Description: Current control relay RM35JA32MW Supply voltage: 24....240V AC/DC Time delay: 0.3....30s Output: 2C/O 5A Control rating: 0.15....15A Function: Under & Overcurrent Width: 35mm

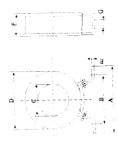


reset time delay (adjustable on front panel) / Fin de la consigne de temporisation (réglable en façade) / Ende des Sollwerts der Verzögerung Instellbar) / Fin de la consigna de temporización (ajustable en fachada) / Fine dell'istruzione di temporizzazione (regolabile sul pannello anteriore)

TIMED MULTIFUNCTION, MULTI-VOLTAGE OR SINGLE-VOLTAGE RELAY - 1 DIN with backlit display



*	• • •		۲	0
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7	2	2	2	В
136	101	78	78	۵
06	60	32	25	υ
78	78	78	78	ß
63	93	93	93	Y
RCT-90	RCT-60	RCT-35	RCT-25	Model
	and the second se	ns(mm):	Oimensio	形尺寸
000/5 2500/	00/5 1600/5 2	00/5 1200/5 15		RCT-110
500/5 1600/:	00/5 1200/5 1	800/5 10		RCT-90
1 2/0001 2/	0/5 600/5 800	300/5 400/5 50		RCT-60
50/5 200/5	100/5 120/5 1	0/5 60/5 80/5	30/5 5	RCT-35
60/5 75/5	0/5 40/5 50/5	15/5A 20/5 3		RCT-25
ondary	格Primary/sec			표 号Model
				Specification:
FS<5		coefficient:	Rated security	底安全轰费
lth=60		rmal current:	Short-time the	短时间热电波
1.0			Class:	辅度等级
15VA			Rated load:	额记母数
50-60F			Frequency:	张 *
0 66K ¹		age:	Maximum volt	最大电压
JEC44-1		val:	Standard approval:	经建业税书
5A. I.A		rent:	Secondary current:	二次电流
AU006-A0;		12	Primary current:	
	0 66KV 50-60Hz 15VA 10VA 100 11-60XIh F5<5 60:5 75:5 100 60:5 75:5 100 60:5 75:5 100 15 1000/5 2500:5 31 93 93 93 90 9136 136 93 93 90 93 93 90 93 93 90 93 93 90 93 93 90 93 93 90 93 93 90 93 93 90 93 93 90 93 93 90 93 93 93 93 93 93 93 93 93 93 93 93 93	0 66K/ 90 66K/ 90 66K/ 90 66K/ 90 66K/ 91 90 100 100 120 500 500 500 500 500 500 500 500 500 5	age: 0 66KV readifican: 0 66KV solding 15VA 15VA 15VA 15VA 15VA 15VA 15VA 15SA 2005 5005 5005 605 5005 2005 2505 3005 4005 5005 5005 5005 2005 2505 3005 4005 5005 5005 10005 12005 3005 10005 12005 15005 2005 25005 3005 10005 12005 10005 12005 75005 300 8005 10005 12005 10005 10005 25005 300 8005 10005 12005 10005 25005 300 8005 1005 12005 10005 25005 300 8005 1005 12005 10005 25005 300 8005 1005 1005 12005 10005 25005 300 8005 1005 1005 10005 2005 2005 300 8005 1005 1005 2005 2005 2005 300 8005 1005 1005 2005 2005 2005 2005 300 8005 1005 2005 10005 2005 2005 2005 300 8005 10005 10005 10005 2005 2005 2005 300 8005 10005 10005 10005 2005 2005 2005 200	add: ioy: coltrand add: 10/5 5 12/5 5 10/5 5 10/5 10/5 5 10/5 10 10/5 10 10/5 10 10/5 10 10 10/5 10 10 10 10/5 10 10 10 10 10 10 10 10 10 10 10 10 10 1



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电流互感器





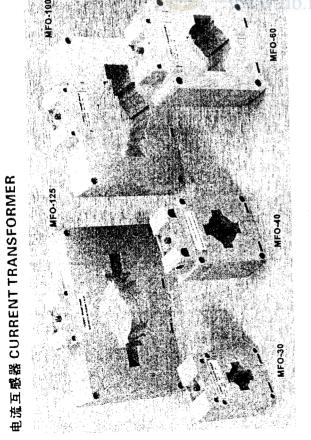






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技术说明 Specifications

開いた	Ratel current (A) Primary/Secondary	Busher hole dimension	Rated burden(VA)	精 庚 Accuracy	載定电压 Rated Voltage (v)	数定频率 Rated Frequency (Ha
12000				2 0~0 5	600	50/60
MPO-JOCT	30/5A-300/5A	30×10mm	1.2-0			COLEN
	1 60/6 4 800/6 A	40 × 10mm	5-10	1.0~0.5	909	No/nc
MF0-40C1	VICING-VCIDC1			1 00	600	50/60
T JOA MAN	400/5A-1200/5A	60×20mm	01-0			
		100 × 10mm	15	1.0~0.5	89	50/60
MFO-100CT	800/2A-30002A			1 0-05	600	50/60
MF0-125CT	1500/5A-5500/5A	125×10000	4	And the second s	And and the second	and a state of the second second second
And the second second second second						

外形尺寸 Outline drawing

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尺寸说明 Dimensions

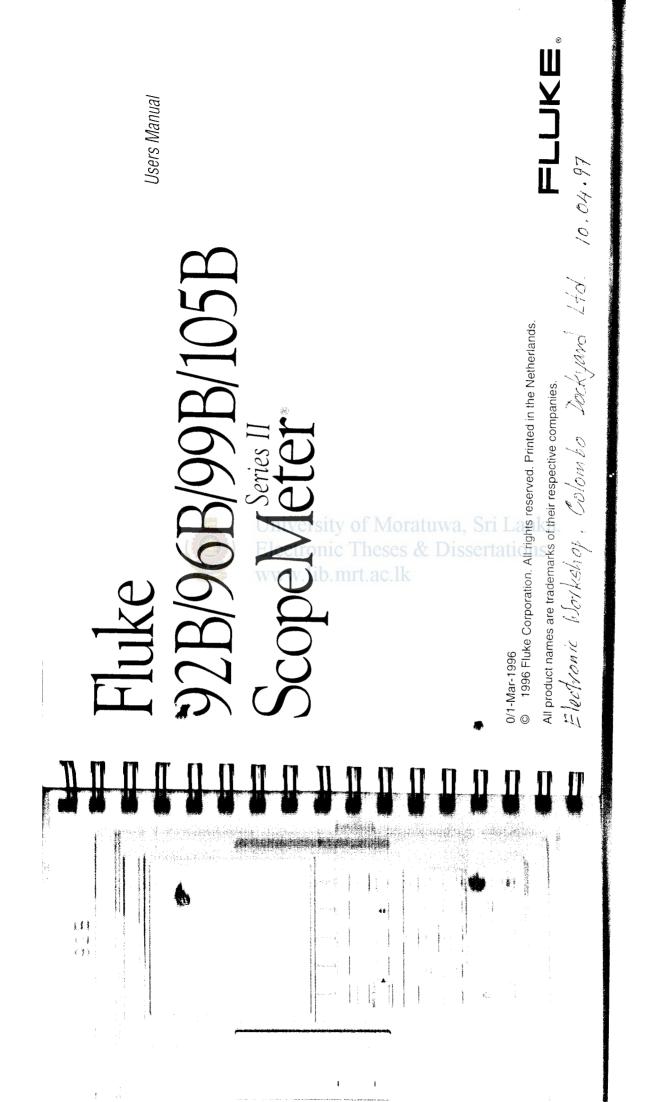
							单位 Unitant	Bittom
호号 Model	۲	æ	JU	a	щ	в.,	Ċ	н
MFO-30(Small)	09	ŝ	67	17	60	31	10	59
MF0-30CT	75	43	82	17	60	31	10	17
MFO-40CT	75	43	82	17	S	31	10	71
MF0-60CT	101	4	Ξ	1	3	31	10	11
MFO-100CT	145	45	139	17	60	31	10	5
MFO-125CT	196	46	210	11	8	34	=	5
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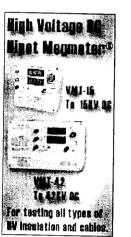


VOLTAGE LEVEL SENSOR

Up

Standard Model

Deluxe Model



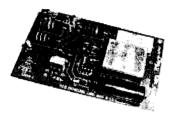


International

B-10

VOLTAGE LEVEL SENSOR / INTERLOCK

Useful for Power Supply Voltage Limiter, Capacitor Charge Level and, under or over Voltage Control, or Indicating.



Ross Engineering Corporation will custom build you voltage level sensor / indicator / interlock from our b building blocks.

Description

For limiting, setting or indicating voltage levels of pc supplies, required charge level for energy storage capacitors, and voltage level interlocking.

Some of the many options available are: S & Dissertations

- High accuracy adjustable trip point.
- High sensor input impedance for internal line or external sensing.
- Extremely fast response or adjustable delay.
- Voltage level sensor can be powered from your AC line or DC source, 5 to 150V DC (If DC source voltage being sensed it must have a common connection), actuate from voltage whose level is being sensed (requires at 0.01 ampere for trip). Can have isolated trip input.
- Voltage level sensor can have transient protection installed.
- AC or positive, zero or negative voltage level can be sensed.
- Voltage levels to ±750 volts can be sensed using resistors mounted interna on printed circuit board.
- Voltage levels greater than ±750 volts can be sensed using external voltag • dividers.
- Voltage levels less than ±1 microvolt can be sensed under optimum condit
- Fixed trip point can be built into voltage level sensor.
- External resistor, or a trimmer potentiometer, or a remote conventional potentiometer may be used to set variable trip point.