Automatic Classification of Multiple Acoustic Events Using Artificial Neural Networks

Dineth Egodage

 $188015\mathrm{M}$

Thesis submitted in partial fulfillment of the requirements for the Degree of Master of Science (Research) in Computer Science and Engineering

Department of Computer Science & Engineering

University of Moratuwa Sri Lanka

January 2021

DECLARATION

I declare that this is my own work and this thesis does not incorporate without acknowledgement any material previously submitted for a Degree or Diploma in any other University or institute of higher learning and to the best of my knowledge and belief it does not contain any material previously published or written by another person except where the acknowledgement is made in the text.

Also, I hereby grant to University of Moratuwa the non-exclusive right to reproduce and distribute my thesis/dissertation, in whole or in part in print, electronic or other medium. I retain the right to use this content in whole or part in future works (such as articles or books).

Signature of the candidate:

Date:

The above candidate has carried out research for the MSc thesis under my supervision.

Name of the supervisor: Signature of the supervisor:

Date :

ACKNOWLEDGEMENTS

First of all, I would like to express my gratitude towards the Department of Computer Science and Engineering offering the Master's Degree programme to perform this kind of work.

Secondly, I would like to express my heartiest gratitude towards my research supervisor Dr. Sulochana Sooriyaarachchi for the guidance and immense support provided in both knowledge and resource-wise to make this research a success.

I would also like to thank Dr. Navinda Kottege and Dr. Chandana Gamage for guiding and advising us to stay on the correct path at the initial stages of this research. The Commonwealth Scientific and Industrial Research Organisation (CSIRO), Australia, should also be mentioned thankfully for providing this research idea and Dr. Kottege as a resource person for us.

Furthermore, I would like to convey my gratitude towards Dr. Sampath Seneviratne from Animal Communications, Genetics, Evolutionary Biology section of the University of Colombo for sharing his expertise domain knowledge and spend his valuable time to guide me through the research.

Besides, I am grateful to the progress panel members, Dr. Ranga Rodgrigo and Dr. Charith Chithrarajan, for giving their valuable feedback on the work carried out.

Finally, I would like to express my gratitude towards Dr. Charith Chithrarajan as the Research Coordinator and all other staff members for the knowledge given throughout the last two years.

Finally, I would like to express my heartiest gratitude towards my friends and family for the immense support given throughout the research. Special thanks to my wife, who remained supportive until the end.

ABSTRACT

There are numerous scenarios where similar acoustic events occur multiple times. Acoustic monitoring of migratory birds is an ideal example. Birds make a type of call known as flight calls during migration. A flight call can be considered as an acoustic event because it is a short-term, intuitively distinct sound. It is challenging to identify multiple occurrences of extremely short-range acoustic events such as flight calls in real-world recordings using classification techniques that require more computational power. It is mainly due to background noise and complex acoustic environments. This research aims at developing a classification model that reduces the effect of background noise, extract ROIs from continuous recordings, extract suitable features of flight calls and detect multiple occurrences of flight calls. An improved algorithm that can extract features has been developed in this research—by combining a well known Maximally Stable Extremal Regions (MSER) technique with state of the art traditional techniques. Namely Spectral and Temporal Features (SATF) and a combination of SATF and Spectrogram-based Image Frequency Statistics(SIFS). We name this novel algorithm as Spectrogram-based Maximally Stable Extremal Regions (SMSER). Three distinct feature sets have formed such that Featureset-1 created using SATF. Featureset-2 is a blend of SATF and SIFS. Featureset-3 is a combination of SATF, SIFS, and SMSER. The kNN, RF, SVM, and DNN classification techniques evaluated a real-world dataset using the extracted feature sets. Research carried out several tests to find out the best performing combination of classification model and feature set. The results showed that the flight calls' detection accuracy increased when the number of features increased, although high computational power requirement is a disadvantage. The performance of SMSER feature set was the best among almost every classification technique above. It should be because the SMSER Feature set has the highest number of features. Classification of the SMSER feature set from the DNN classifier showed the highest accuracy of 87.67%.

LIST OF FIGURES

| Figure 1.1 | Syrinx of a bird and its placement[1] | 2 |
|-------------|--|----|
| Figure 1.2 | Comparison of current tools to study migration | 5 |
| Figure 1.3 | Breakdown of previous research done in flight call classification | 6 |
| Figure 2.1 | Mel-Filterbank | 15 |
| Figure 2.2 | Conversion of Log-Mel-Spectrogram into a Binary Image. | 19 |
| Figure 3.1 | Overall system design | 25 |
| Figure 3.2 | Spectrogram of Flight call with Noise | 29 |
| Figure 3.3 | Spectrogram of Flight call after applying High-pass Butterworth | |
| | Filter and Spectral Subtraction | 29 |
| Figure 3.4 | Conversion of Log-Mel-Spectrogram into a Binary Image. | 36 |
| Figure 3.5 | Static margin from 10% to 60% and ROI extracted from 60% margin | 38 |
| Figure 3.6 | Pseudo code of SMSER algorithm | 39 |
| Figure 3.7 | Samples of detected contours using the SMSER algorithm. | 39 |
| Figure 3.8 | Spectral Centroid distribution over a 30 frames segment | 44 |
| Figure 3.9 | Basic recipe for Neural Networks | 49 |
| Figure 4.1 | Spectrogram of a flight call | 56 |
| Figure 4.2 | Spectrogram of a flight call after noise reduction | 57 |
| Figure 4.3 | Recursive Feature Elimination with Cross-Validation with RF and | |
| | SVM classifiers for Feature set 1 | 59 |
| Figure 4.4 | Feature Importance Score | 60 |
| Figure 4.5 | Visualizing the Feature Importance Variable in RF for the Feature | |
| | set 1 | 61 |
| Figure 4.6 | 2 Component PCA for Feature set 1 | 62 |
| Figure 4.7 | 3 Component PCA for Feature set 1 | 63 |
| Figure 4.8 | Accuracy against SVM with Polynomial kernel Degree Parameter | |
| | for Feature set 1 | 64 |
| Figure 4.9 | Accuracy against No. of trees in RF algorithm for Feature set 1 | 64 |
| Figure 4.10 | Accuracy against Value of k in kNN algorithm for Feature set 1 | 65 |

| Figure 4.11 | kNN results of MFCC_Mean_8 against other high importance | |
|-------------|---|----|
| | features | 66 |
| Figure 4.12 | Accuracy against No. of epoch for DNN algorithm for Feature set 1 | 66 |
| Figure 4.13 | Accuracy vs feature sets along with the classifier used | 67 |

LIST OF TABLES

| Table 4.1 | Classification Accuracy of Feature set 1 from 4 different SVM ker- | |
|-----------|---|----|
| | nels | 60 |
| Table 4.2 | Classification Accuracy of All the Feature sets from SVM RBF kernel $% \mathcal{A}$ | 61 |
| Table 4.3 | Classification Accuracy of All the Feature sets from RF Classifier | |
| | with 180 trees | 62 |
| Table 4.4 | Classification Accuracy of All the Feature sets from kNN Classifier | |
| | with $k = 11$ | 65 |
| Table 4.5 | Classification Accuracy of All the Feature sets from DNN Classifier | 67 |
| Table 4.6 | Comparison of Related and Current work of flight call classification | 68 |

LIST OF ABBREVIATIONS

- ANN Artificial Neural Networks
- DNN Deep Neural Network
- DFT Discrete Fourier Transformation
- DWTC Discrete Wavelet Transform Coefficients
- FFT Fast Fourier Transformation
- GMM Gaussian Mixture Models
- GPU Graphics Processing Unit
- HMM Hidden Markov Models
- k-NN k-Nearest Neighbor
- MFCC Mel Frequency Cepstral Coefficients
- PC Personal Computer
- PCA Principal Component Analysis
- RF Random Forest Algorithm
- RFE Recursive Feature Elimination
- RMSE Root Mean Square Energy
- SATF Spectral and Temporal Features
- SIFS Spectrogram-based Image Frequency Statistics
- SMSER Spectrogram-based Maximally Stable Extremal Regions
- SVM Support Vector Machine
- ZCR Zero-Crossing Rate

TABLE OF CONTENTS

| List of Figures | | iv | | |
|-------------------|-----------------------|-------------------------|--|-----|
| Lis | st of ' | Tables | | vi |
| Lis | List of Abbreviations | | | vii |
| Table of Contents | | | | |
| 1 | Introduction | | 1 | |
| | 1.1 | Background | | 1 |
| | 1.2 | Problem | | 8 |
| | 1.3 | Resear | rch Objectives | 8 |
| | 1.4 | Contri | ibutions | 8 |
| | 1.5 | Thesis | s Outline | 9 |
| 2 | Lite | Literature Review | | 10 |
| | 2.1 | Flight | calls | 10 |
| | 2.2 | Prepro | ocessing and Segmentation | 11 |
| | 2.3 | Feature Extraction | | 13 |
| | | 2.3.1 | Mel-Frequency Cepstral Coefficients (MFCC) | 13 |
| | | 2.3.2 | Standard Temporal and Spectral Features | 16 |
| | | 2.3.3 | Novel Features | 18 |
| | 2.4 | Classi | fication | 20 |
| | | 2.4.1 | Classification of bird vocalization as Time-series | 20 |
| | | 2.4.2 | Segment-wise Classification of Bird Vocalizations | 22 |
| 3 | Methodology | | 25 | |
| | 3.1 | Overview of Methodology | | 25 |
| | 3.2 | Dataset | | 26 |
| | | 3.2.1 | CLO-43SD | 26 |
| | | 3.2.2 | CLO-SWTH and CLO-WTSP | 26 |
| | | 3.2.3 | BirdVox-full-night | 26 |
| | 3.3 | Pre-pr | rocessing and Noise reduction | 27 |
| | | 3.3.1 | High-pass Butterworth Filter | 28 |

| | | 3.3.2 | Spectral Subtraction | 29 |
|----|----------------|-------------|---|----|
| | 3.4 | ROI E | Extraction | 30 |
| | | 3.4.1 | Zero Crossing $Rate(ZCR)$ | 30 |
| | | 3.4.2 | Instantaneous Energy Threshold | 31 |
| | | 3.4.3 | Short Time Energy Threshold | 32 |
| | 3.5 | Featu | re Extraction and Selection | 32 |
| | | 3.5.1 | Feature set 1 | 33 |
| | | 3.5.2 | Feature set 2 | 36 |
| | | 3.5.3 | Feature set 3 | 38 |
| | | 3.5.4 | Frame Base Extraction of Features | 42 |
| | | 3.5.5 | Feature Reduction and Selection | 43 |
| | 3.6 | Classi | fication Models | 45 |
| | | 3.6.1 | Recognition of Flight Calls | 45 |
| 4 | Exp | eriment | tal Evaluation and Discussion of Results | 50 |
| | 4.1 | Data Set | | |
| | 4.2 | Experiments | | 51 |
| | | 4.2.1 | Supervised Learning Methods | 54 |
| | | 4.2.2 | Deep Learning Method | 55 |
| | 4.3 | Result | ts and Evaluation | 56 |
| | | 4.3.1 | Evaluation of Noise reduction techniques | 56 |
| | | 4.3.2 | Evaluation of RoI Extraction Techniques | 57 |
| | | 4.3.3 | Evaluation of Feature Selection and Reduction | 57 |
| | | 4.3.4 | Evaluation of Supervised Classification Models | 59 |
| | | 4.3.5 | Evaluation of Deep Learning Classification Models | 65 |
| | 4.4 Discussion | | 67 | |
| 5 | Con | clusion | | 69 |
| Re | References | | | 71 |