

DECLARATION

The work submitted in this thesis is the result of my own investigation, except where otherwise stated.

It has not already been accepted for any degree, and is also not being concurrently submitted for any other degree.



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23rd March 2009

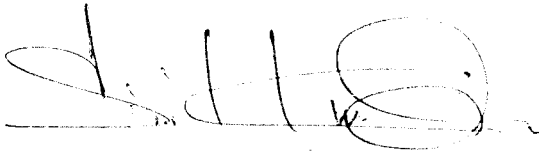


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I endorse the declaration by the candidate.



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ACRONYMS

USV	-	Unmanned Surface Vehicles
UGV	-	Unmanned Ground Vehicles
DAMN	-	Distributed Architecture for Mobile Navigation
GPS	-	Global Position System
INU	-	Inertial Navigation Unit
PFM	-	Potential field method
VOM	-	Velocity Obstacle method
DNC	-	Digital Nautical Chart
GRNN	-	Generalized Regression Neural Network



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