

# VUEBLOX: A Semi-Supervised Hybrid Deep Learning Framework for Occlusion-Aware and Interpretable Crowd Anomaly Detection

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## I. INTRODUCTION

Crowd tracking using computer vision technologies enhances public safety, but detecting crowd anomalies remains challenging due to issues like occlusion and interpretability models' low accuracy [1]. Also, those are irregularly happening constitute a small percentage, so the datasets have lots of missing labeled outliers. This study address these gaps by proposing a semi-supervised hybrid architecture with dedicated modules for occlusion and interpretability.

## II. LITERATURE REVIEW

Over time, research on crowd anomaly detection has changed dramatically. As deep learning has advanced, methods that use variational autoencoders [2] and convolutional neural networks have shown better results. Though [3] emphasizes the significance of part-based models and attention processes for managing visual obstructions in pedestrian detection. Semi-supervised learning approaches have emerged to address data scarcity challenges, with methods like AnoRand demonstrating how random labeling strategies can improve anomaly detection performance.

### A. Taxonomy of crowd anomaly detection techniques

As shown in Figure 1 the author has presented two primary methods for detecting anomalies in crowds: frame extraction-based anomaly detection and crowd density-driven anomaly identification.

## III. METHODOLOGY

System architecture has a pipeline structure and consists six components, which are inter-linked with each other.

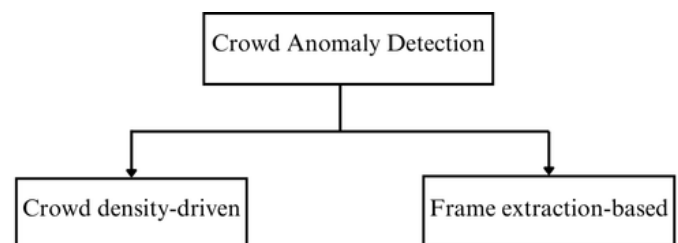


Fig. 1. Taxonomy of crowd anomaly detection techniques

### A. Input Video Acquisition

The process of the pipeline is initiated by the acquisition of video data as the only input source for the system.

### B. Preprocessing

Frame extraction, normalization, noise reduction, and background subtraction are the primary preprocessing operation [4]. As a result, the video is transformed from raw data to standardized frames.

### C. Occlusion Handling

This module implements an architecture based on a transformer, processing of patches, as well as the application of a GAN inpainting system, to recover the areas which are occluded in crowded scenes. Spatial relationships are modeled by Graph Neural Networks [5].

### D. Feature Extraction

The characteristics concerning the video content consists of four techniques applied. Specifically, SimCLR employs self-supervised contrastive learning [6]. The sparse tracking techniques are selected based on the movement patterns. Graph Neural Networks depicts the interactions, and Long-Term Memory networks handle the sequence of frame features to unveil unusual patterns.

### E. Anomaly Detection

It uses hybrid techniques, which are ensemble voting and threshold-based scoring strategies to hunt down the abnormal occurrences with high precision. This method utilizes multiple detection models, weighted voting, and dynamic confidence score adjustment to ensure that the detection is robust to environment.

### F. Interpretability

Interpretation includes Grad-CAM attention maps, graph-based explanations, and prototype-based anomaly association. Those technologies give graphic and text-based demonstrations, outlining localities influencing anomaly result [7].

## IV. RESULTS

Author applied the model to evaluate precision, F1-score, AUC, and occlusion robustness. Occlusion-handling module trained on the MOT dataset, and it lasted 7 hours due to limited computational resources. The full end-to-end system needed 24 hours on a mid-range GPU. Without interpretability modules 20 FPS can go high.

TABLE I  
SOTA APPROACHES COMPARISON IN TERMS OF COMPUTATIONAL TIME ON UCSD PED2 DATASET

| Approaches        | Computational time |
|-------------------|--------------------|
| 150 FPS [8]       | 27FPS              |
| SF [9]            | 25FPS              |
| AMDN [10]         | 25FPS              |
| sRNN-AE [11]      | 25FPS              |
| <b>Our method</b> | <b>20FPS</b>       |

TABLE II  
PERFORMANCE COMPARISON OF CROWD ANOMALY DETECTION METHODS

| Method                     | Precision    | F1-score     | AUC          | Occlusion Robust |
|----------------------------|--------------|--------------|--------------|------------------|
| Transfer Learning [12]     | 0.731        | 0.671        | 0.798        | Low              |
| Semantic Segmentation [13] | 0.924        | 0.238        | 0.884        | Medium           |
| Graph-based Detection [14] | 0.941        | 0.256        | 0.902        | Medium           |
| Hybrid Pixel-Frame [15]    | 0.957        | 0.243        | 0.894        | Low              |
| <b>Ours</b>                | <b>0.990</b> | <b>0.269</b> | <b>0.929</b> | <b>High</b>      |

## V. CONCLUSION

VUEBLOX serves as a semi-supervised framework to detect crowd anomalies through explainability and occlusion. While the system producing promising outcomes the framework still poses significant challenges because of limited computational resources and shows dataset biases. Rich explanations and enhanced complex occlusion management result in a reduction

of FPS. System will focus on merging various behavioral signals while enhancing edge-based systems and improving performance across data domains.

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